

# Kvaser U100 User's Guide



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## 1 About this manual

This manual is intended for Kvaser U100 users. This document contains a description of the hardware's properties and general instructions for connecting the device to a computer.

## 2 Introduction

This section will describe the functions and features of the Kvaser U100.

### 2.1 Welcome to Kvaser U100



Figure 1: Kvaser U100

Kvaser U100 is a small, yet powerful, CAN to USB interface. It provides real-time transmission and reception of standard and extended CAN messages on the bus with a high timestamp precision, and is compatible with applications that use Kvaser's CANlib.

This guide applies to Kvaser U100 devices using at least firmware and driver versions listed in Table 1. For minimum compatible firmware and driver versions of Kvaser U100 see Table 6 on Page 13.

Device	Product Number	Firmware	Driver (Windows/Linux)
Kvaser U100	73-30130-01173-1	v3.24	v5.36 (kcany/mhydra)

Table 1: Firmware and driver versions needed to support all functionality present in this guide.

## 2.2 Major features of Kvaser U100

- USB CAN interface.
- Powered through the USB connector.
- Supports CAN FD, up to 8 Mbit/s (with correct physical layer implementation).
- Supports both 11-bit (CAN 2.0A) and 29-bit (CAN 2.0B active) identifiers.
- Lightweight robust housing made of glass fibre reinforced polyamide overmolded with TPE.
- Intuitive LED UI.
- Reinforced galvanic isolation, design validated with 5000 VAC rms applied for 60 s.
- Industrial grade temperature range,  $-40^{\circ}\text{C}$  to  $+85^{\circ}\text{C}$ .
- 20 000 msg/s, each timestamped with a resolution of 100  $\mu\text{s}$ .
- Fully compatible with applications written for other Kvaser CAN hardware with Kvaser CANlib.
- Support for SocketCAN.
- Fully compatible with J1939, CANopen, NMEA 2000<sup>®</sup> and DeviceNet.
- IP67 rated housing.

## 3 Kvaser U100 hardware

In this section you can read more about the CAN channels, power supply and LED indicators.

### 3.1 Hardware installation

The Kvaser U100 may be inserted in any free USB socket on the host computer. You do not need to switch the power off before inserting or removing the device. For the Kvaser U100 to communicate with the host computer, a compatible version of the Kvaser driver and firmware must be installed.

The driver is installed by running the file `kvaser_drivers_setup.exe`. For instructions on how to update the firmware, see Section 3.8, Updating the firmware, on Page 13. The latest version of the driver and firmware can be downloaded from [www.kvaser.com/download](http://www.kvaser.com/download).

The firmware is downloaded and installed directly on the Kvaser U100 and the driver is installed on the host computer. After the driver has been installed on the host computer, the firmware may then be downloaded and installed on the Kvaser U100.

### 3.2 USB connection

The USB connector for the Kvaser U100 is a standard USB type “A” connector (see Figure 2).



Figure 2: A standard USB type “A” connector.

Connect the device to your computer using any high quality USB 2.0 certified cable. The maximum USB cable length is 5 m (~ 16 ft). If you need a longer cable,

you can use USB hubs or USB extension cables with a built-in hub. By chaining up to 5 hubs, you can achieve an effective cable length of up to 25 m (~ 82 ft).



As USB cables become longer they are more sensitive to EMI, because they make a longer antenna that can pick up more noise. These issues can be mitigated by using higher quality cables with better shielding. Thicker cables tend to be better than thin ones, and braided shielding tends to be more reliable than only foil. Furthermore, longer cables may introduce signal degradation and timing issues that, if necessary, can be mitigated using shorter cable segments combined with hubs that amplify the signal and handle delays on a per-cable basis.

### 3.3 CAN connection

The Kvaser U100 has one CAN channel.

The CAN connector for the Kvaser U100 is the 9-pin D-SUB connector (see Figure 3) which has the pinout described in Table 2 on Page 9.



Figure 3: The 9-pin D-SUB CAN connector.

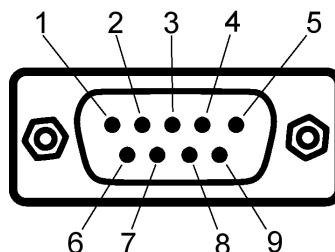


Figure 4: The 9-pin D-SUB connector pinout.



D-SUB pin	Function
1	Not connected
2	CAN_L
3	GND
4	Not connected
5	Shield
6	Not connected
7	CAN_H
8	Not connected
9	Not connected

Table 2: Configuration of the 9-pin D-SUB connector.

### 3.4 CAN bus termination

Every CAN bus must be terminated with a 120 Ohm resistor at each end of the bus. The Kvaser U100 does not contain any CAN bus termination, because their inclusion could cause severe disturbance in a system which is already correctly terminated.

For laboratory or testing use, the exact value of the termination resistors is not always critical. Sometimes a single terminator is sufficient. For production, proper termination is essential. If you see error frames on the bus, you should check the termination.



**To save yourself a lot of trouble, always terminate the CAN bus properly.**

### 3.5 Power supply

The Kvaser U100 is powered through the USB connector.

### 3.6 LED Indicators

A Kvaser U100 device has two traffic LED bars where part of each LED bar is also used as a status area. The TX LED Bar has a status area towards the USB end of the bar, and the RX LED bar has a status area towards the CAN end of the bar. This is shown in Figure 5.

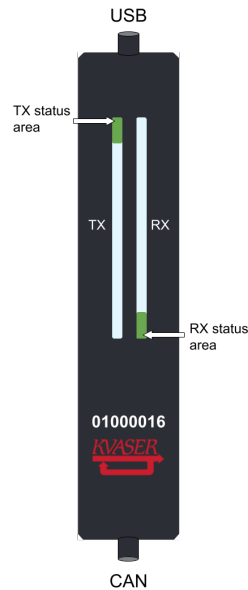


Figure 5: The TX and RX LED bars on the Kvaser U100 include status areas.

Different colors are used for different types of information and different blink patterns define the current state, see Table 3 and Table 4 on Page 11.

Color	Information type
Yellow	Traffic
Green	Status
Red	Error
White	Alert
Blue	System

Table 3: Different types of information.

State	Definition
Off	The indicator is off and no light is emitted.
Slow Blink	The indicator is repeatedly turned on and off. The on and off phases are equal in time.
Fast Blink	The indicator is repeatedly turned on and off but with a higher frequency than Slow Blink. The on and off times are still equal.
On	The indicator is constantly emitting light.
Dynamic	The indicator is moving and/or increasing/decreasing in size.

Table 4: Definitions of the indicator states.

### 3.7 Interface mode

The device is in interface mode when connected to a computer via USB. If the status area is presenting a steady white light, the device is in interface mode, working correctly and ready to be used. When connected to a computer for the first time, the status area will Fast Blink with blue light until the Kvaser Drivers are installed and the device has automatically received a USB configuration. The status area will change from white to green when going bus on. Table 5 summarises the information shown in interface mode.

Description	Status area	LED bar
Power is on	On (White)	-
Waiting for USB configuration	Fast Blink (Blue)	-
CAN channel is bus on	On (Green)	-
CAN channel traffic	On (Yellow)	Dynamic (Yellow)
Error frame	-	Dynamic (Red)
CAN channel is error passive	Fast Blink (Red)	-
CAN overrun	On (Red)	-
Firmware update	Slow Blink (Blue)	-
Locate hardware	Slow Blink (White)	Slow Blink (White)

Table 5: LED indications in interface mode.

The Kvaser U100 has one TX LED Bar and one RX LED Bar. Each LED Bar has a status area, the TX LED Bar has a status area towards the USB end of the bar, and the RX LED bar has a status area towards the CAN end of the bar. This is shown in Figure 5 on Page 10.

The TX LED bar lit area grows from the USB end of the LED bar towards the CAN end of the bar as CAN TX traffic is increased. Likewise, the RX LED bar lit area grows from the CAN end of the LED bar towards the USB end of the bar as the message rate of the received traffic is increased, see Figure 6 on Page 12. In this example the unit is transmitting data, which shows a yellow TX status area. No CAN traffic is received and as such the RX status area is green.

The total size of the LED bars are indicating the current bus load, e.g. Figure 6 on Page 12 shows only receiving CAN messages at 50% bus load. Figure 7 on



Figure 6: The TX LED bar lights up from the USB side to the CAN side of the unit, while the RX LED bar lights up from the CAN side to the USB side of the unit.

Page 12 shows two different bus load conditions. The image on the left shows the unit transmitting and receiving data corresponding to 50% bus load in each direction for a total of 100% bus load. The image on the right shows the unit transmitting data corresponding to 100% bus load.

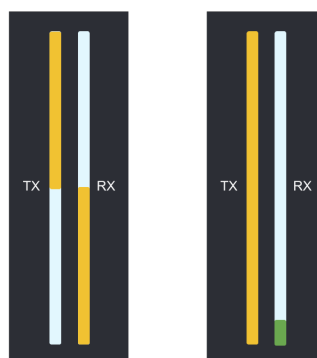


Figure 7: The total size of the LED Bars is proportional to the bus load. Both images indicate a bus load of 100%.

### 3.8 Updating the firmware

For the Kvaser U100 to communicate with the host computer, compatible versions of the Kvaser CANlib (including driver) and firmware must be installed.

The latest versions of firmware and drivers can be downloaded for free at [www.kvaser.com/download](http://www.kvaser.com/download).

Connect the Kvaser U100 to your PC with the USB cable and start the update.exe application. A window opens showing the Firmware Update Instructions, read and follow those carefully.

To check the current firmware version, open "Kvaser Device Guide" which can be found in the Control Panel. Select "Kvaser U100" in the tree view to the left, and click on the channel. The firmware revision information now appears in the right half of the window.

The absolute minimum firmware and driver versions needed in order to use Kvaser U100 are listed in Table 6

Device	Min. Firmware Version	Min. Driver Version
Kvaser U100	v3.22.578	v5.31

Table 6: Minimum compatible driver and firmware versions of Kvaser U100.

### 3.9 Technical data

In Table 7 below you will find the Kvaser U100's technical specifications.

CAN Channels	1
CAN Transceivers	ADM3055E (Compliant with ISO 11898-2)
CAN Controller	Built into the processor.
Galvanic isolation	Yes, reinforced. Design validated with 5000 VAC rms applied for 60 s.
CAN Bit Rate	10 kbit/s to 1 Mbit/s
CAN FD Bit Rate	Up to 8 Mbit/s (with correct physical layer implementation).
Time stamp resolution	100 $\mu$ s
Max message rate	20 000 msg/s per channel
Error Frame Detection	Yes
Error Frame Generation	No
Silent mode	No
Kvaser MagiSync	No
Kvaser <i>t</i> programming	No
Kvaser CANtegrity	No
PC interface	USB 2.0
Power consumption	Typical 250 mA
Software requirements	Windows (7 or later), Linux
Dimensions	38 x 128 x 26 mm for body
Cable length	USB 1.0 m, CAN 0.3 m
Weight	170 g including connectors
Operating temperature	-40 °C to +85 °C
Storage temperature	-40 °C to +85 °C
Relative humidity	0% to 85% (non-condensing)
IP Rating Housing	IP67
IP Rating CAN connector	IP40 Mated
IP Rating USB connector	IP40 Mated

Table 7: Technical Specifications

## 4 Troubleshooting

Use “Kvaser Device Guide” in the Control Panel to verify that the computer can communicate with the Kvaser U100. If the firmware version shown is all zeros, there are communication problems. If the LED Bar or the status indication is not flashing or does not light up at all, check the power supply.

## 5 Safety Instructions

### 5.1 Intended Use

Kvaser CAN Interfaces are used to connect computer systems to CAN networks. The Kvaser U100 is intended for connection to a computer via the USB interface.

### 5.2 Usage Warning



#### **WARNING FOR ALL USERS**

WARNING! - YOUR USE OF THIS DEVICE MUST BE DONE WITH CAUTION AND A FULL UNDERSTANDING OF THE RISKS!

THIS WARNING IS PRESENTED TO INFORM YOU THAT THE OPERATION OF THIS DEVICE MAY BE DANGEROUS. YOUR ACTIONS CAN INFLUENCE THE BEHAVIOR OF A CAN-BASED DISTRIBUTED EMBEDDED SYSTEM, AND DEPENDING ON THE APPLICATION, THE CONSEQUENCES OF YOUR IMPROPER ACTIONS COULD CAUSE SERIOUS OPERATIONAL MALFUNCTION, LOSS OF INFORMATION, DAMAGE TO EQUIPMENT, AND PHYSICAL INJURY TO YOURSELF AND OTHERS. A POTENTIALLY HAZARDOUS OPERATING CONDITION IS PRESENT WHEN THE FOLLOWING TWO CONDITIONS ARE CONCURRENTLY TRUE: THE PRODUCT IS PHYSICALLY INTERCONNECTED TO A REAL DISTRIBUTED EMBEDDED SYSTEM; AND THE FUNCTIONS AND OPERATIONS OF THE REAL DISTRIBUTED EMBEDDED SYSTEM ARE CONTROLLABLE OR INFLUENCED BY THE USE OF THE CAN NETWORK. A POTENTIALLY HAZARDOUS OPERATING CONDITION MAY RESULT FROM THE ACTIVITY OR NON-ACTIVITY OF SOME DISTRIBUTED EMBEDDED SYSTEM FUNCTIONS AND OPERATIONS, WHICH MAY RESULT IN SERIOUS PHYSICAL HARM OR DEATH OR CAUSE DAMAGE TO EQUIPMENT, DEVICES, OR THE SURROUNDING ENVIRONMENT.

WITH THIS DEVICE, YOU MAY POTENTIALLY:

- CAUSE A CHANGE IN THE OPERATION OF THE SYSTEM, MODULE, DEVICE, CIRCUIT, OR OUTPUT.
- TURN ON OR ACTIVATE A MODULE, DEVICE, CIRCUIT, OUTPUT, OR FUNCTION.
- TURN OFF OR DEACTIVATE A MODULE, DEVICE, CIRCUIT, OUTPUT, OR FUNCTION.
- INHIBIT, TURN OFF, OR DEACTIVATE NORMAL OPERATION.
- MODIFY THE BEHAVIOR OF A DISTRIBUTED PRODUCT.
- ACTIVATE AN UNINTENDED OPERATION.
- PLACE THE SYSTEM, MODULE, DEVICE, CIRCUIT, OR OUTPUT INTO AN UNINTENDED MODE.

ONLY THOSE PERSONS WHO:

(A) ARE PROPERLY TRAINED AND QUALIFIED WITH RESPECT TO THE USE OF THE DEVICE,

(B) UNDERSTAND THE WARNINGS ABOVE, AND

(C) UNDERSTAND HOW THIS DEVICE INTERACTS WITH AND IMPACTS THE FUNCTION AND SAFETY OF OTHER PRODUCTS IN A DISTRIBUTED SYSTEM AND THE APPLICATION FOR WHICH THIS DEVICE WILL BE APPLIED, MAY USE THE DEVICE.

PLEASE NOTE THAT YOU CAN INTEGRATE THIS PRODUCT AS A SUBSYSTEM INTO HIGHER-LEVEL SYSTEMS. IN CASE YOU DO SO, KVASER AB HEREBY DECLARES THAT KVASER AB'S WARRANTY SHALL BE LIMITED TO THE CORRECTION OF DEFECTS, AND KVASER AB HEREBY EXPRESSLY DISCLAIMS ANY LIABILITY OVER AND ABOVE THE REFUNDING OF THE PRICE PAID FOR THIS DEVICE, SINCE KVASER AB DOES NOT HAVE ANY INFLUENCE ON THE IMPLEMENTATIONS OF THE HIGHER-LEVEL SYSTEM, WHICH MAY BE DEFECTIVE.



## 6 Disposal and Recycling Information



When this product reaches its end of life, please dispose of it according to your local environmental laws and guidelines.

For information about Kvaser's recycling programs, visit:  
<https://www.kvaser.com/en/kvaser/recycling-policy.html>



## 7.2 FCC Regulatory Compliance



### Federal Communications Commission (FCC) Compliance Information Statement

**IDENTIFICATION OBJECT:**

Product: Kvaser U100  
Type: 73-30130-01173-1

**APPLICABLE COMPLIANCE STATEMENTS:**

CFR Title 47 Part 15 §15.107, §15.109

This device complies with part 15 of the FCC Rules.

Operation is subject to the following two conditions:

- (1) This device may not cause harmful interference, and
- (2) this device must accept any interference received, including interference that may cause undesired operation.

**RESPONSIBLE PARTY (IN USA) NAME:**

Kvaser Inc.  
23881 Via Fabricante, Suite 503  
Mission Viejo, CA 92691

Internet contact: [support@kvaser.com](mailto:support@kvaser.com)

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DeviceNet is a trademark of Open DeviceNet Vendor Association, Inc.

NMEA 2000 is the registered trademark of the National Marine Electronics Association, Inc.

For information about Kvaser related CAN patents, see [www.kvaser.com/patent](http://www.kvaser.com/patent).

## 8 Document Revision History

Version history for document UG\_98223\_U100:

Revision	Date	Changes
1.0	2021-01-11	Initial version
1.1	2021-05-19	New layout, added connector IP class, updated LED indications.
1.2	2021-09-09	Dropped mention of Hi-Speed CAN